

CBCS SCHEME

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18MR651

Sixth Semester B.E. Degree Examination, Jan./Feb. 2023

Automation and Industrial Robotics

Time: 3 hrs.

Max. Marks: 100

Note: Answer any FIVE full questions, choosing ONE full question from each module.

Module-1

- 1 a. Define Automation. Explain basic elements of Automated System, with block diagram. (10 Marks)
 b. What is the difference between a Closed loop control system and Open loop control system? (10 Marks)

OR

- 2 a. Explain levels of Automation. (10 Marks)
 b. What is a Sensor? Differentiate between analog and discrete sensor , passive and active sensor. (10 Marks)

Module-2

- 3 a. With neat diagram, explain Walking beam mechanism. (10 Marks)
 b. What is Storage Buffer? Why Storage buffers are required in automated production lines? (10 Marks)

OR

- 4 a. Explain different components of parts delivery system. (10 Marks)
 b. List and briefly explain the AIDC technologies. (10 Marks)

Module-3

- 5 a. With sketches, explain different types of joints used in robots. (10 Marks)
 b. Which are Robot Configurations? Explain Cartesians Coordinate robot with sketch. (10 Marks)

OR

- 6 a. List and explain application of Industrial Robots. (10 Marks)
 b. Briefly explain Asimov's laws of Robotics and define Dynamic Stabilization of Robot. (10 Marks)

Module-4

- 7 a. Write a note on Description of a position and description of an Orientation. (10 Marks)
 b. What is Mapping? Write a note on mappings involving translated frames. (10 Marks)

OR

- 8 a. Write a note on Actuator space, Joint space and Cartesian space. (10 Marks)
 b. Explain the Link - Frame attachment procedure. (10 Marks)

Module-5

- 9 a. Explain the levels of Robot Programming, with example. (10 Marks)
 b. How do you classify Robot Programming Languages? Explain Task – Level Programming Languages. (10 Marks)

OR

- 10 a. List out the requirements of a Robot Programming Language and explain briefly. (10 Marks)
 b. What are the central issues in OLP system? Briefly explain. (10 Marks)

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